

# A DC programming framework for portfolio selection by minimizing the transaction costs

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# Problem description

- $n$  assets: the return on asset  $i$  is  $a_i$  (random variable)  
 $a = (a_1, \dots, a_n)$ ,  $\mathbf{E}(a) = \bar{a}$ ,  $\mathbf{E}(a - \bar{a})(a - \bar{a})^T = \Sigma$ .
- $w = (w_1, \dots, w_n)^T$ : current holdings
- $x_i$ : amount transacted in asset  $i$ ,  
 $x_i > 0$  for buying,  $x_i < 0$  for selling,  
 $x = (x_1, \dots, x_n)^T$ : portfolio selection.
- Adjusted portfolio  $w + x$   
 $\implies$  The wealth at the end of the period:  $W = a^T(w + x)$ ,  
 $\mathbf{E}W = \bar{a}^T(w + x)$ ,  $\mathbf{E}(W - \mathbf{E}W)^2 = (w + x)^T \Sigma (w + x)$
- Shortselling constraints:  $w_i + x_i \geq -s_i$ ,  $\forall i$  where  $s_i \geq 0$   
Constraint on Expected return:  $\bar{a}^T(w + x) \geq r_{\min}$   
Constraint on Variance:  $(w + x)^T \Sigma (w + x) \leq \sigma_{\max}^2$   
Diversification constraints:  $w_i + x_i \leq \lambda_i \mathbf{1}^T (w + x)$ ,  $\forall i$ ,  $\lambda_i \geq 0$

# Mathematical formulation

## Problem ( $P$ )

$$\left\{ \begin{array}{l} \min \phi(x) = \sum_{i=1}^n \phi_i(x_i) \\ \text{s.t. } \bar{a}(w + x) \geq r_{\min} \\ w_i + x_i \geq -s_i, \forall i \\ w_i + x_i \leq \lambda_i \mathbf{1}^T (w + x), \forall i \\ (w + x)^T \Sigma (w + x) \leq \sigma_{\max}^2 \end{array} \right. \quad \text{or} \quad \min \left\{ \phi(x) = \sum_{i=1}^n \phi_i(x_i) \mid x \in C \right\}$$

$\phi_i$  is the transaction cost function for asset  $i$  given by

$$\phi_i(x_i) = \begin{cases} 0, & x_i = 0 \\ \beta_i - \alpha_i^1 x_i, & x_i < 0 \\ \beta_i + \alpha_i^2 x_i, & x_i > 0 \end{cases} \quad (\beta_i, \alpha_i^1, \alpha_i^2 \geq 0, \forall i)$$

# Mathematical formulation

## Problem ( $P$ )

$$\left\{ \begin{array}{l} \min \phi(x) = \sum_{i=1}^n \phi_i(x_i) \\ \text{s.t. } \bar{a}(w+x) \geq r_{\min} \\ w_i + x_i \geq -s_i, \forall i \\ w_i + x_i \leq \lambda_i \mathbf{1}^T (w+x), \forall i \\ (w+x)^T \Sigma (w+x) \leq \sigma_{\max}^2 \end{array} \right. \quad \text{or} \quad \min \left\{ \phi(x) = \sum_{i=1}^n \phi_i(x_i) \mid x \in C \right\}$$

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# DC programming and DCA: DC program

DC = Difference of Convex functions

DC program

$$(P_{dc}) \quad \inf\{f(x) = g(x) - h(x) \mid x \in \mathbb{R}^n\}$$

( $g, h$ : lower semicontinuous proper convex functions on  $\mathbb{R}^n$ )

$g - h$ : a *DC decomposition* of  $f$ .

$g, h$ : *convex DC components* of  $f$ .

$g^*, h^*$ : *conjugate functions* of  $g, h$ .

$$g^*(y) := \sup\{\langle x, y \rangle - g(x) \mid x \in \mathbb{R}^n\}, \quad y \in \mathbb{R}^n$$

Subdifferential of a convex function  $\theta$  at  $x_0 \in \text{dom} f$

$$(\text{dom} f := \{x \in \mathbb{R}^n : \theta(x) \leq +\infty\})$$

$$\partial\theta(x_0) := \{y \in \mathbb{R}^n : \theta(x) \geq \theta(x_0) + \langle x - x_0, y \rangle, \forall x \in \mathbb{R}^n\}$$

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# DC programming and DCA: DC Algorithm

DCA = DC algorithm

Constructing two sequences  $\{x^k\}$  et  $\{y^k\}$ , candidates to be solutions of  $(P_{dc})$  and its dual program respectively

Generic DCA scheme

Initial point  $x^0 \in \text{dom}g$ ,  $k \leftarrow 0$

Repeat:

$$\begin{array}{c} x^k \longrightarrow y^k \in \partial h(x^k) \\ \swarrow \\ x^{k+1} \in \partial g^*(y^k) \longrightarrow y^{k+1} \in \partial h(x^{k+1}) \end{array}$$

Until: convergence of  $\{x^k\}$ .

$$x^{k+1} \in \partial g^*(y^k) \iff$$

$$x^{k+1} \in \arg \min \{g(x) - \langle x, y^k \rangle \mid x \in \mathbb{R}^n\}$$

# BB: methods for global optimization for nonconvex problems

- *Lower bounds:* Found from convex relaxation, duality, Lipschitz or other bounds,...
- *Upper bounds:* can be found by choosing any point in the region, or by a local optimization method.
- *Basic idea:*
  - partition feasible set into convex sets, and find lower/upper bounds for each
  - form global lower and upper bounds; quit if close enough
  - else, refine partition and repeat

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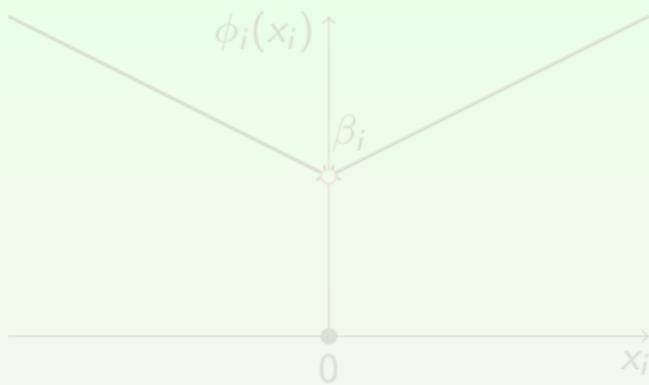
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# Method 1: Solving ( $P$ ) by DCA



$$\phi_i(x_i) = \begin{cases} 0, & x_i = 0 \\ \beta_i - \alpha_i^1 x_i, & x_i < 0 \\ \beta_i + \alpha_i^2 x_i, & x_i > 0 \end{cases}$$

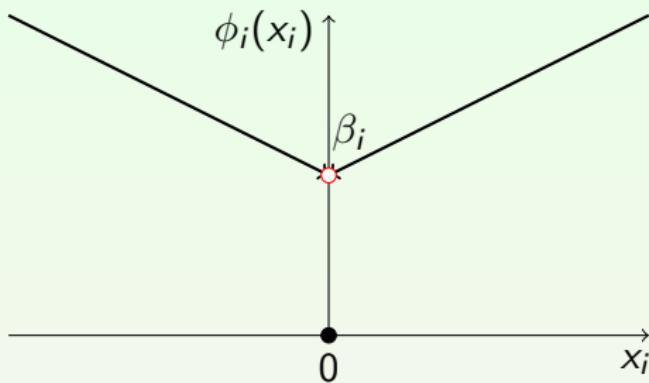
$$\phi(x) = \sum_{i=1}^n \phi_i(x_i)$$



$$f_i(x_i) = \begin{cases} \beta_i - \alpha_i^1 x_i, & x_i \leq -\epsilon_i \\ -c_i^1 x_i, & -\epsilon_i \leq x_i \leq 0 \\ c_i^2 x_i, & 0 \leq x_i \leq \epsilon_i \\ \beta_i + \alpha_i^2 x_i, & x_i \geq \epsilon_i \end{cases}$$

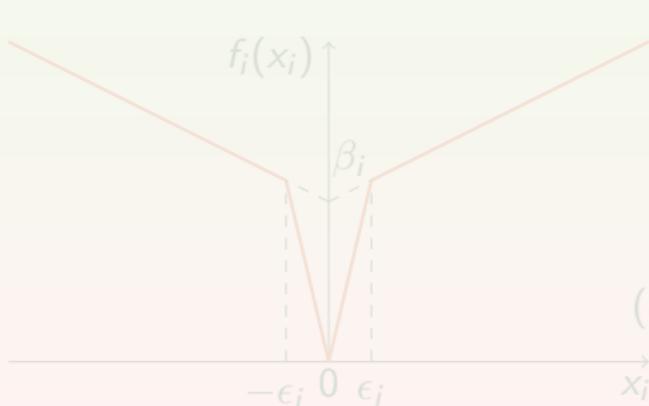
$$(c_i^j = \frac{\beta_i}{\epsilon_i} + \alpha_i^j) \quad f(x) = \sum_{i=1}^n f_i(x_i)$$

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$$\phi_i(x_i) = \begin{cases} 0, & x_i = 0 \\ \beta_i - \alpha_i^1 x_i, & x_i < 0 \\ \beta_i + \alpha_i^2 x_i, & x_i > 0 \end{cases}$$

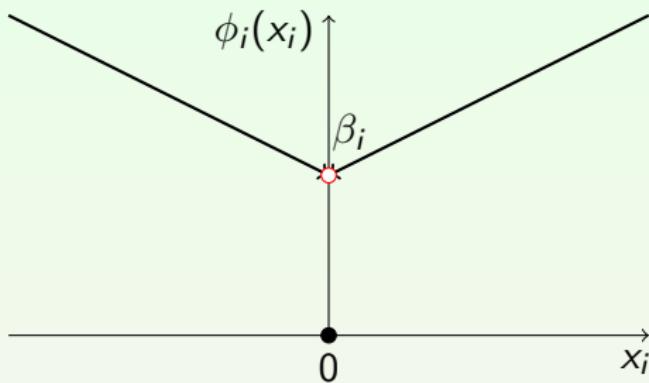
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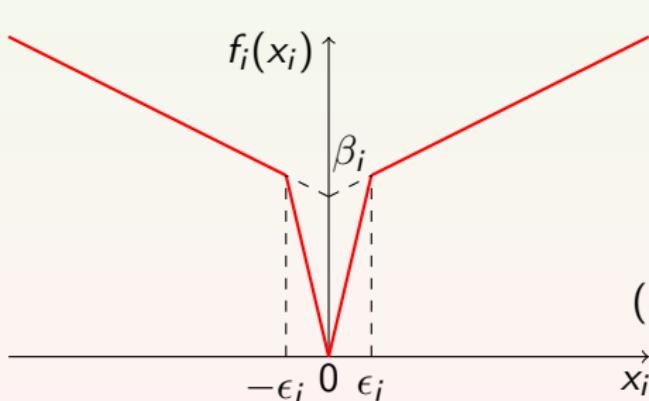
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# Method 1: Solving ( $P$ ) by DCA



$$\phi_i(x_i) = \begin{cases} 0, & x_i = 0 \\ \beta_i - \alpha_i^1 x_i, & x_i < 0 \\ \beta_i + \alpha_i^2 x_i, & x_i > 0 \end{cases}$$

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$$(c_i^j = \frac{\beta_i}{\epsilon_i} + \alpha_i^j) \quad f(x) = \sum_{i=1}^n f_i(x_i)$$

# Method 1: Solving ( $P$ ) by DCA

$$f(x) = \sum_{i=1}^n f_i(x_i)$$

- $f$  is a polyhedral DC function
- $f(x) \leq \phi(x), \forall x \in C$
- A DC approximation program of ( $P$ ) is

$$(P_{dc}) \quad \min\{f(x) = \sum_{i=1}^n f_i(x_i) = g(x) - h(x) \mid x \in C \cap R_0\}$$

- Solving ( $P_{dc}$ ) by DCA to find a solution for ( $P$ )

(DCA has a finite convergence for polyhedral DC programs)

## Method 2: Solving ( $P$ ) by DCA-B&B



$$\phi_i(x_i) = \begin{cases} 0, & x_i = 0 \\ \beta_i - \alpha_i^1 x_i, & x_i < 0 \\ \beta_i + \alpha_i^2 x_i, & x_i > 0 \end{cases}$$

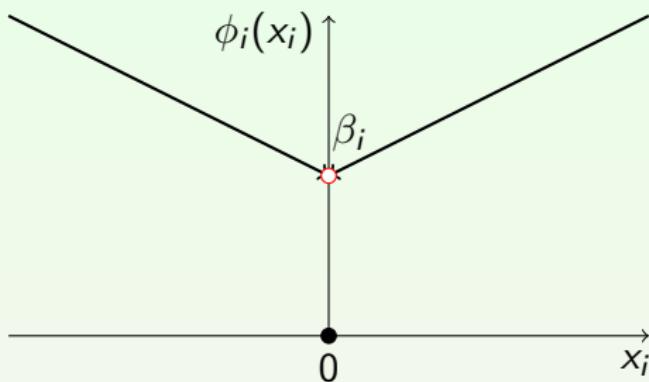
$$l_i^0 = \min\{x_i \mid x \in C\}$$

$$u_i^0 = \max\{x_i \mid x \in C\}$$



$$\tilde{\phi}_i(x_i) = \begin{cases} \left(\frac{\beta_i}{l_i^0} - \alpha_i^1\right)x_i, & x_i \leq l_i^0 \\ \left(\frac{\beta_i}{u_i^0} + \alpha_i^2\right)x_i, & x_i \geq u_i^0 \end{cases}$$

## Method 2: Solving ( $P$ ) by DCA-B&B



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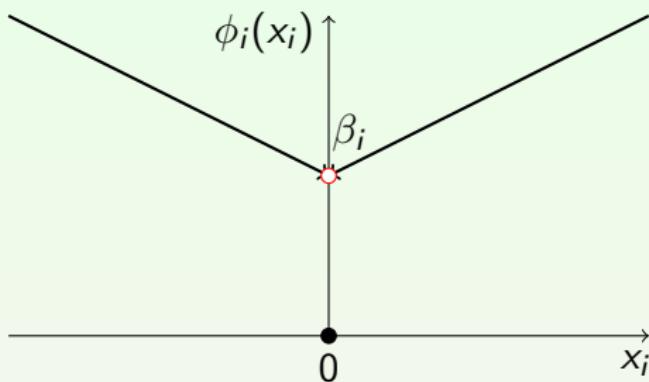
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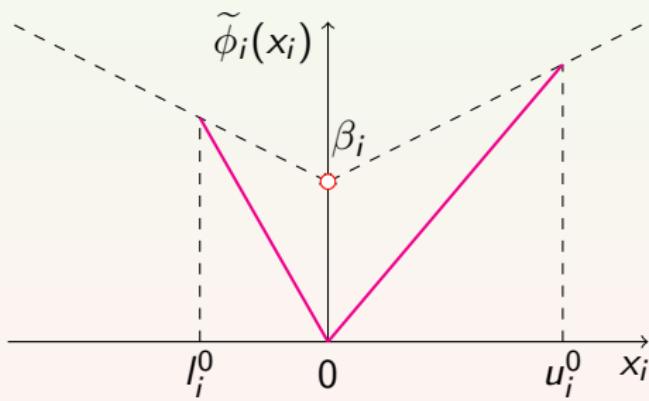
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$$l_i^0 = \min\{x_i \mid x \in C\}$$

$$u_i^0 = \max\{x_i \mid x \in C\}$$



$$\tilde{\phi}_i(x_i) = \begin{cases} \left(\frac{\beta_i}{l_i^0} - \alpha_i^1\right)x_i, & x_i \leq 0 \\ \left(\frac{\beta_i}{u_i^0} + \alpha_i^2\right)x_i, & x_i \geq u_i^0 \end{cases}$$

## Method 2: Solving ( $P$ ) by DCA-B&B

Iteration  $k$ :

$$R_k = \{x \in R_0 \mid x_i = 0 \ \forall i \in I_k, \ x_j \neq 0 \ \forall j \in J_k\} \subset R_0 = [l^0, u^0]$$

$$I_k, J_k \subset \{1, 2, \dots, n\} \quad (I_0 = \emptyset, J_0 = \emptyset).$$

**Subproblem** of ( $P$ ) at iteration  $k$  :

$$(P_k) \quad \omega_k = \min \left\{ \sum_{j \in J_k} \overline{\phi_j}(x_j) + \sum_{i \notin I_k \cup J_k} \phi_i(x_i) \mid x \in C \cap R_0, x_i = 0, \forall i \in I_k \right\}$$

Lower bound  $\eta(R_k)$ : relaxation problem ( $R_k cp$ ) of ( $P_k$ )

$$\eta(R_k) = \min \left\{ \sum_{j \in J_k} \overline{\phi_j}(x_j) + \sum_{i \notin I_k \cup J_k} \widetilde{\phi}_i(x_i) \mid x \in C \cap R_0, x_i = 0, \forall i \in I_k \right\}$$

Let  $x^{R_k}$  be a solution of ( $R_k cp$ ).

If  $\phi(x^{R_k}) <$  the best upper bound  $\implies$  construct a DC approximation program of ( $P_k$ ):

## Method 2: Solving ( $P$ ) by DCA-B&B

$$(R_k^{dc}) \quad \min \left\{ \left( \sum_{j \in J_k} \bar{\phi}_j(x_j) + \sum_{i \notin I_k \cup J_k} g_i(x_i) \right) - \left( \sum_{i \notin I_k \cup J_k} h_i(x_i) \right) \mid x \in C \cap R_0, x_i = 0, \forall i \in I_k \right\}$$

Solving  $(R_k^{dc})$  by DCA, let  $x_{dc}^{R_k}$  be a solution.

Upper bound  $\gamma_k$

$$\gamma_k = \min\{\phi(x^{R_k}), \phi(x_{dc}^{R_k})\}$$

Subdivision process

- Choose an index  $i^*$  such that  $i^* \in \arg \max_i \{\phi_i(x_i^{R_k}) - \tilde{\phi}_i(x_i^{R_k})\}$
- $I_{k_1} := I_k \cup \{i^*\}, J_{k_1} := J_k$  et  $I_{k_2} := I_k, J_{k_2} := J_k \cup \{i^*\}$
- $R_{k_1} = \{x \in R_k, x_{i^*} = 0\} = \{x \in R_0 \mid x_i = 0 \forall i \in I_{k_1}, x_j \neq 0 \forall j \in J_{k_1}\}$   
 $R_{k_2} = \{x \in R_k, x_{i^*} \neq 0\} = \{x \in R_0 \mid x_i = 0 \forall i \in I_{k_2}, x_j \neq 0 \forall j \in J_{k_2}\}$

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## Numerical results: Data

$n$  assets:  $n^{th}$  is a riskless asset

The mean and covariance of  $(n - 1)$  risky assets were estimated from daily closing prices of S&P 500 stocks.

The mean of riskless asset is set to be 0.1.

$$w_i = 1/n, \forall i = 1, \dots, n$$

$$\alpha_i^1 = \alpha_i^2 = \alpha_i = 0.01, \forall i = 1, \dots, n-1, \quad \alpha_n^1 = \alpha_n^2 = \alpha_n = 0$$

$$\beta_i = 0.1/(n-1), \forall i = 1, \dots, n-1, \quad \beta_n = 0$$

$$s_i = 5\beta_i, \forall i = 1, \dots, n-1, \quad s_n = 0.5$$

$$\lambda_i = 0.5, \forall i = 1, \dots, n.$$

Tolerance to stop DCA:  $\varepsilon = 10^{-8}$

The stopping criteria of BB algorithm (with DCA or without DCA) is either CPU time (in seconds)  $\geq 1$  hour or UB-LB  $\leq 10^{-8}$

# Numerical results

n	BB			DCA (Algorithme 1)			DCA-BB (Algorithme 2)				
	iter	Opt.val	CPU(s)	iter	valDCA	CPU(s)	iter	restart	DCA	Opt.val	CPU(s)
101	4877	0.083683	1573.743	2	0.086818	0.374	4877	9	0.083683	1609.035	
111	189	0.084263	51.995	2	0.084967	0.640	189	9	0.084263	56.690	
121	316	0.084130	106.190	2	0.084734	0.765	316	8	0.084130	116.230	
131	298	0.083862	101.924	2	0.084424	1.778	298	6	0.083862	113.374	
141	495	0.083775	181.563	2	0.084254	0.936	495	3	0.083775	191.194	
151	364	0.083678	139.508	2	0.084109	1.640	364	4	0.083678	142.824	
161	612	0.083593	281.261	2	0.083982	1.912	612	4	0.083593	288.858	
171	721	0.083516	519.326	2	0.083867	2.158	525	4	0.083516	428.666	
181	986	0.083447	788.477	2	0.083765	2.586	563	3	0.083447	448.256	
191	1135	0.083386	982.932	2	0.0836755	2.898	713	2	0.083386	759.186	
201	1643	0.083329	1781.377	2	0.083592	2.839	751	2	0.083329	848.047	

Table : Minimize the transaction costs

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191	1135	0.083386	982.932	2	0.0836755	2.898	713	2	0.083386	759.186	
201	1643	0.083329	1781.377	2	0.083592	2.839	751	2	0.083329	848.047	

Table : Minimize the transaction costs

# Thank you for attention!